Celestial mechanics in Kerr spacetime

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Outline

1 Gravitational waves

2 EMRIs and the gravitational self-force

3 Geodesic motion in Kerr spacetime

4 Beyond the geodesic approximation



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1 Gravitational waves

2 EMRIs and the gravitational self-force

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What is a gravitational wave ?

A gravitational wave is a tiny ripple in the curvature of spacetime that propagates at the vacuum speed of light



Key prediction of Einstein's general theory of relativity

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The gravitational-wave spectrum



Gravitational-wave science

Fundamental physics

- Strong-field tests of GR
- Black hole no-hair theorem
- Cosmic censorship conjecture
- Dark energy equation of state
- Alternatives to general relativity

Astrophysics

- Formation and evolution of compact binaries
- Origin and mechanisms of γ -ray bursts
- Internal structure of neutron stars

Cosmology

- Cosmography and measure of Hubble's constant
- Origin and growth of supermassive black holes
- Phase transitions during primordial Universe

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Ground-based interferometric detectors





LVT151012

GW170814 //////

GW170817 ------



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Need for accurate template waveforms



If the expected signal is known in advance then n(t) can be filtered and h(t) recovered by matched filtering \longrightarrow template waveforms

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A recent example: the event GW151226



[PRL 116 (2016) 241103]

LISA: a gravitational antenna in space



The *LISA mission* proposal was accepted by ESA in 2017 for L3 slot, with a launch planned for 2034 [http://www.lisamission.org]

LISA sources of gravitational waves



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Extreme mass ratio inspirals



- LISA sensitive to $M_{
 m BH} \sim 10^5 10^7 M_\odot
 ightarrow q \sim 10^{-7} 10^{-4}$
- $T_{
 m orb} \propto M_{
 m BH} \sim$ hr and $T_{
 m insp} \propto M_{
 m BH}/q \sim$ yrs







(Credit: S. Drasco)

Botriomeladesy





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Test of the black hole no-hair theorem

Botriomeladesy





(Credit: S. Drasco)

$$M_{\ell} + iS_{\ell} = M(ia)^{\ell}$$

M_{ℓ} arbitrary

Testing the black hole no-hair theorem



[PRD 95 (2017) 103012]

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- Dissipative component ↔ gravitational waves
- Conservative component \longleftrightarrow some secular effects



(Credit: Osburn et al. 2016)

Spacetime metric



Spacetime metric

 $g_{\alpha\beta} = g_{\alpha\beta}$

Small parameter

$$q\equiv rac{m}{M}\ll 1$$



Spacetime metric

$$g_{\alpha\beta} = g_{\alpha\beta} + h_{\alpha\beta}$$

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Gravitational self-force

$$\dot{u}^{\alpha} \equiv u^{\beta} \nabla_{\beta} u^{\alpha} = f^{\alpha}[h]$$



Metric perturbation

$$h_{lphaeta} = h_{lphaeta}^{ ext{direct}} + h_{lphaeta}^{ ext{tail}}$$



z^{μ}

Metric perturbation

$$h_{lphaeta} = h_{lphaeta}^{\mathsf{direct}} + h_{lphaeta}^{\mathsf{tail}}$$

MiSaTaQuWa equation

$$\dot{u}^{\alpha} = \underbrace{\left(g^{\alpha\beta} + u^{\alpha}u^{\beta}\right)}_{\text{projector} \perp u^{\alpha}} \underbrace{\left(\frac{1}{2}\nabla_{\beta}h^{\text{tail}}_{\lambda\sigma} - \nabla_{\lambda}h^{\text{tail}}_{\beta\sigma}\right)u^{\lambda}u^{\sigma}}_{\text{"force"}}$$

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c_{ur}

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Beware: the self-force is gauge-dependant

Generalized equivalence principle





(Credit: A. Pound)

body's field $h_{\alpha\beta}$

singular field $h_{\alpha\beta}^S$

regular field $h^R_{\alpha\beta}$

Generalized equivalence principle







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body's field $h_{\alpha\beta}$

singular field $h_{\alpha\beta}^S$

regular field $h^R_{\alpha\beta}$

singular/self field

$$h^{S} \sim m/r$$
$$\Box h^{S} \sim -16\pi T$$
$$f^{\alpha}[h^{S}] = 0$$

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Generalized equivalence principle





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body's field $h_{\alpha\beta}$

singular field $h^S_{lphaeta}$

regular field $h^R_{\alpha\beta}$

singular/self field

regular/residual field

$$h^{S} \sim m/r \qquad \qquad h^{R} \sim h^{\text{tail}} + \text{local terms}$$
$$\Box h^{S} \sim -16\pi T \qquad \qquad \Box h^{R} \sim 0$$
$$f^{\alpha}[h^{S}] = 0 \qquad \qquad \dot{u}^{\alpha} = f^{\alpha}[h^{R}]$$
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self-acc. motion in $g_{\alpha\beta} \iff$ geodesic motion in $g_{\alpha\beta} + h_{\alpha\beta}^R$

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Canonical Hamiltonian

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Constants of motion

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• Ang. mom.
$$L = \phi^{lpha} u_{lpha} = u_{\phi}$$

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- Carter constant $Q = K^{lphaeta} u_{lpha} u_{eta}$

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Generalized action-angle variables

[Carter, PRD 1968; Schmidt, CQG 2002]

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Generalized action-angle variables

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- Canonical transfo. to *coordinate-invariant* action-angle variables (w^{α}, J_{α}) , with $w^{i} + 2\pi \equiv w^{i}$ and

$$J_{t} = \frac{1}{2\pi} \int_{0}^{2\pi} u_{t} dt = -E, \quad J_{r} = \frac{1}{2\pi} \oint u_{r}(r) dr$$
$$J_{\phi} = \frac{1}{2\pi} \oint u_{\phi} d\phi = L, \qquad J_{\theta} = \frac{1}{2\pi} \oint u_{\theta}(\theta) d\theta$$

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$$J_t = \frac{1}{2\pi} \int_0^{2\pi} u_t \, \mathrm{d}t = -E \,, \quad J_r = \frac{1}{2\pi} \oint u_r(r) \, \mathrm{d}r$$
$$J_\phi = \frac{1}{2\pi} \oint u_\phi \, \mathrm{d}\phi = L \,, \qquad J_\theta = \frac{1}{2\pi} \oint u_\theta(\theta) \, \mathrm{d}\theta$$

• Hamilton's canonical equations of motion for H(J):

$$\dot{w}^{\alpha} = \left(\frac{\partial H}{\partial J_{\alpha}}\right)_{w} \equiv \omega^{\alpha}, \quad \dot{J}_{\alpha} = -\left(\frac{\partial H}{\partial w^{\alpha}}\right)_{J} = 0$$

Hamiltonian first law of mechanics

[Le Tiec, CQG 2014]

• Varying H(J) and using Hamilton's equations, as well as the on-shell constraint $H = -\frac{1}{2}$, yields the variational formula

 $\delta H = \omega^{\alpha} \delta J_{\alpha} = 0$

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• Since $H(\lambda J) = \lambda^2 H(J)$, we also have the algebraic relation

$$\omega^{\alpha} J_{\alpha} = \frac{\partial H}{\partial J_{\alpha}} J_{\alpha} = 2H = -1$$

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• Using non-specific variables $\mathcal{J}_{\alpha} \equiv m J_{\alpha}$ and the fundamental *t*-frequencies $\Omega^{\alpha} \equiv \omega^{\alpha} / \omega^{t} \equiv z \, \omega^{\alpha}$, this gives

$$\delta \mathcal{E} = \Omega^{\varphi} \, \delta \mathcal{L} + \Omega^{r} \, \delta \mathcal{J}_{r} + \Omega^{\theta} \, \delta \mathcal{J}_{\theta} + z \, \delta m$$

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• We consider only the *conservative piece* of the self-force:

$$h^R_{lphaeta} = rac{1}{2} ig(h^{
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 The geodesic motion of a self-gravitating mass m in the metric g_{αβ}(x) + h^R_{αβ}(x; γ) derives from the Hamiltonian

$$H(x, u; \gamma) = \underbrace{H_{(0)}(x, u)}_{\frac{1}{2}g^{\alpha\beta}(x)u_{\alpha}u_{\beta}} + \underbrace{H_{(1)}(x, u; \gamma)}_{-\frac{1}{2}h_{R}^{\alpha\beta}(x; \gamma)u_{\alpha}u_{\beta}}$$

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- Canonical transform. to action-angle variables (w^{lpha}, J_{lpha})
- Hamilton's canonical equations of motion for $H(w, J; \gamma)$:

$$\dot{w}^{\alpha} = \left(\frac{\partial H}{\partial J_{\alpha}}\right)_{w} \equiv \omega^{\alpha}, \quad \dot{J}_{\alpha} = -\left(\frac{\partial H}{\partial w^{\alpha}}\right)_{J} \neq 0$$

No secular change in the actions

• For any function f of the canonical variables (x, u) we define the long (proper) time average

$$\langle f \rangle \equiv \lim_{T \to \infty} \frac{1}{2T} \int_{-T}^{T} f(x(\tau), u(\tau)) \,\mathrm{d}\tau$$

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• The rate of change \dot{J}_{α} of the actions can be split into an average piece and an oscillatory component:

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angle+\delta\dot{J}_{lpha}$$
 with $ig\langle\delta\dot{J}_{lpha}ig
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• The average rate of change of the actions vanishes:

$$\left\langle \dot{J}_{\alpha}\right\rangle = -\left\langle \left(\frac{\partial H_{(1)}}{\partial w^{\alpha}}\right)_{J}\right\rangle = 0$$

Gauge transformations

A gauge transformation x^α → x^α + ξ^α induces a canonical transformation with generator Ξ(x, u) = u_αξ^α(x) such that

$$\delta_{\xi} x^{\alpha} = \left(\frac{\partial \Xi}{\partial u_{\alpha}}\right)_{x}, \quad \delta_{\xi} u_{\alpha} = -\left(\frac{\partial \Xi}{\partial x^{\alpha}}\right)_{u}$$

Gauge transformations

• A gauge transformation $x^{\alpha} \to x^{\alpha} + \xi^{\alpha}$ induces a canonical transformation with generator $\Xi(x, u) = u_{\alpha}\xi^{\alpha}(x)$ such that

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• The action-angle variables (w^{α}, J_{α}) are affected by this gauge transformation in a similar manner:

$$\delta_{\xi} \mathbf{w}^{\alpha} = \left(\frac{\partial \Xi}{\partial J_{\alpha}}\right)_{\mathbf{w}}, \quad \delta_{\xi} J_{\alpha} = -\left(\frac{\partial \Xi}{\partial \mathbf{w}^{\alpha}}\right)_{J}$$

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• Despite that, we have the *gauge-invariant* identity:

$$\dot{w}^{\alpha}J_{\alpha} = \omega^{\alpha}J_{\alpha} = -1$$

• Neither the action variables nor the fundamental frequencies are gauge invariant:

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• The relationship between the average redshift $z \equiv 1/\langle \omega^t \rangle$ and the average *t*-frequencies $(\Omega^r, \Omega^\theta, \Omega^\phi)$ is gauge-invariant

A special gauge choice

• The gauge freedom allows us to choose a gauge such that

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• Additionally, the gauge-invariant interaction Hamiltonian $H_{int}(J) \propto \langle H_{(1)} \rangle$ is required to satisfy

$$\left\langle \left(\frac{\partial H_{(1)}}{\partial J_{\alpha}}\right)_{w}\right\rangle = \frac{1}{2}\frac{\partial H_{\text{int}}}{\partial J_{\alpha}}$$

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$$\left\langle \left(\frac{\partial H_{(1)}}{\partial J_{\alpha}}\right)_{w}\right\rangle = \frac{1}{2}\frac{\partial H_{\text{int}}}{\partial J_{\alpha}}$$

These gauge conditions can indeed be imposed consistently

An effective Hamiltonian

• In this particular gauge, Hamilton's equations of motion take the remarkably simple form

$$\dot{w}^{lpha} = \omega^{lpha} = \omega^{lpha}_{(0)}(J) + rac{1}{2}rac{\partial \mathcal{H}_{ ext{int}}}{\partial J_{lpha}}, \quad \dot{J}_{lpha} = 0$$

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$$\mathcal{H}(J) = H_{(0)}(J) + \frac{1}{2}H_{\text{int}}(J)$$

• Despite the freedom to change the constant actions J_{α} by a gauge transformation, this effective Hamiltonian is *unique*
First law of mechanics

Using the effective Hamiltonian *H(J)*, the test-mass *first law* of mechanics can be extended to relative *O(q)*:

$$\delta \tilde{\mathcal{E}} = \Omega^{\varphi} \, \delta \tilde{\mathcal{L}} + \Omega^{r} \, \delta \tilde{\mathcal{J}}_{r} + \Omega^{\theta} \, \delta \tilde{\mathcal{J}}_{\theta} + z \, \delta m$$

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• It involves the renormalized actions and the average redshift

$$\begin{split} \tilde{\mathcal{J}}_{\alpha} &\equiv m \tilde{J}_{\alpha} \equiv m J_{\alpha} \left(1 - \frac{1}{2} \mathcal{H}_{\text{int}} \right) \\ z &= z_{(0)} + z_{(1)} = z_{(0)} \left(1 + \mathcal{H}_{\text{int}} \right) \end{split}$$

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The actions *J*_α and the average redshift *z*, as functions of (Ω^r, Ω^θ, Ω^φ), include conservative self-force corrections from the gauge-invariant interaction Hamiltonian *H*_{int}

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5 Innermost stable circular orbits



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• The innermost stable circular orbit is identified by a vanishing restoring radial force under small-*e* perturbations:

$$rac{\partial^2 H}{\partial r^2} = 0 \quad \longrightarrow \quad \Omega_{
m isco}$$

• The minimum energy circular orbit is the most bound orbit along a sequence of circular orbits:

$$rac{\partial E}{\partial \Omega} = 0 \quad \longrightarrow \quad \Omega_{meco}$$

• For Hamiltonian systems, it can be shown that

$$\Omega_{\text{isco}} = \Omega_{\text{meco}}$$



Kerr ISCO frequency vs black hole spin

[Bardeen et al., ApJ 1972]



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Spins of supermassive black holes

[Reynolds, CQG 2013]



Frequency shift of the Kerr ISCO

[Isoyama et al., PRL 2014]

• The orbital frequency of the Kerr ISCO is shifted under the effect of the conservative self-force:

$$(M+m)\Omega_{\rm isco} = \underbrace{M\Omega_{\rm isco}^{(0)}(\chi)}_{\substack{\rm test \ mass \\ \rm result}} \left\{ 1 + \underbrace{q \ C_{\Omega}(\chi)}_{\substack{\rm self-force \\ \rm correction}} + \mathcal{O}(q^2) \right\}$$

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- The frequency shift can be computed from a stability analysis of slightly eccentric orbits near the Kerr ISCO
- Combining the Hamiltonian first law with the MECO conditio $\partial E/\partial \Omega = 0$ yields the same result:

$$\mathcal{C}_{\Omega} = rac{1}{2} \, rac{z_{(1)}''(\Omega_{
m isco}^{(0)})}{E_{(0)}''(\Omega_{
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[Isoyama et al., PRL 2014]



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[van de Meent, PRL 2017]





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